# **Revised Criteria for Stability in the General Two-Higgs Doublet Model**

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### Abstract

We will revise one of the methods given in the literature to determine the necessary and sufficient conditions that the parameters must satisfy to have a stable scalar potential in the general two-Higgs doublet model (THDM). We will give a procedure that facilitates finding the conditions for stability of a scalar potential. The stability guarantees that the scalar potential has a global minimum, that is, the potential is bounded from below, which is a necessary condition to implement the spontaneous gauge-symmetry breaking in the models.

#### Introduction **Stability** $\Lambda(\lambda)$ stable potential: bounded from below Stability <sup>2</sup>< 0 stability determined by V in limit $K_0 \rightarrow \infty$ , • consider $V_4$ for $K_0 > 0$ , define: $\mathbf{k} \equiv \mathbf{K}/K_0$ , with $|\mathbf{k}| \leq 1.$

# **Example: Stability for THDM**

THDM of Gunion et al., with the Higgs potential  $V(\varphi_1,\varphi_2) = \lambda_1 \left(\varphi_1^{\dagger}\varphi_1 - v_1^2\right)^2 + \lambda_2 \left(\varphi_2^{\dagger}\varphi_2 - v_2^2\right)^2$  $+\lambda_3\left(arphi_1^\daggerarphi_1-v_1^2+arphi_2^\daggerarphi_2-v_2^2
ight)^2$  $+ \lambda_4 \left( (arphi_1^\dagger arphi_1) (arphi_2^\dagger arphi_2) - (arphi_1^\dagger arphi_2) (arphi_2^\dagger arphi_1) 
ight)$  $+\lambda_5 \left(\operatorname{Re}(\varphi_1^{\dagger}\varphi_2) - v_1 v_2 \cos \xi\right)^2$  $+\lambda_6 \left( \operatorname{Im}(\varphi_1^{\dagger}\varphi_2) - v_1 v_2 \sin \xi \right)^2$  $+\lambda_7 \left(\operatorname{Re}(\varphi_1^{\dagger}\varphi_2) - v_1 v_2 \cos \xi\right) \left(\operatorname{Im}(\varphi_1^{\dagger}\varphi_2) - v_1 v_2 \sin \xi\right),$ 



# **THDM Higgs Potential**

 Two complex Higgs-doublet fields with hypercharge y = +1/2:  $arphi_1(x) = egin{pmatrix} arphi_1(x) \ arphi_1(x) \end{pmatrix}, \qquad arphi_2(x) = egin{pmatrix} arphi_2^+(x) \ arphi_2^0(x) \end{pmatrix}.$ 



 Renormalisable, gauge invariant potential contains only

 $(\varphi_i^{\mathsf{T}}\varphi_j)(\varphi_k^{\mathsf{T}}\varphi_l), \quad i, j, k, l \in \{1, 2\}$  $\varphi_i^! \varphi_j,$ **Definition:** orbit variables  $K_0, K_1, K_2, K_3$ :  $\begin{pmatrix} \varphi_1^{\mathsf{T}} \varphi_1 & \varphi_2^{\mathsf{T}} \varphi_1 \\ \varphi_1^{\mathsf{T}} \varphi_2 & \varphi_2^{\mathsf{T}} \varphi_2 \end{pmatrix} \equiv \frac{1}{2} (K_0 \mathbb{1} + K_a \sigma^a) \Leftrightarrow$  $K_0 = \varphi_1^{\dagger} \varphi_1 + \varphi_2^{\dagger} \varphi_2, \ K_1 = 2 \operatorname{\mathsf{Re}} \varphi_1^{\dagger} \varphi_2,$ 

- $V_4 = K_0^2 J_4(\boldsymbol{k}), \quad J_4(\boldsymbol{k}) \equiv \eta_{00} + 2\eta^T \mathbf{k} + \boldsymbol{k}^T E \mathbf{k}$
- stability guaranteed by  $V_4 \Leftrightarrow J_4(\mathbf{k}) > 0$  for all  $|\boldsymbol{k}| \leq 1$
- domain of  $J_4$  is unit ball: compact  $J_4 > 0 \Leftrightarrow J_4|_{stat} > 0$  for all its stationary points
- stationary points of  $J_4(\mathbf{k}) \equiv \eta_{00} + 2\eta^T \mathbf{k} + \mathbf{k}^T E \mathbf{k}$ on domain  $\mathbf{k}^2 \leq 1$ 
  - $|\mathbf{k}| < 1$ : solve  $\nabla_{\mathbf{k}} J_4(\mathbf{k}) = 0 \quad \Leftrightarrow \mathbf{E}\mathbf{k} = -\eta$ , with  $1 - k^2 > 0$ ,
  - $|\mathbf{k}| = 1$ : define  $F_4(\mathbf{k}, u) \equiv J_4(\mathbf{k}) + u(1 \mathbf{k}^2)$ , with Lagrange multiplier u, solve  $\nabla_k F_4(\boldsymbol{k}, u) = 0 \Leftrightarrow (\boldsymbol{E} - \boldsymbol{u})\boldsymbol{k} = -\eta$ , with  $1 - k^2 = 0$ .

# **Revised criteria for stability**

#### The deepest minimum

Suppose we find two solutions p and q with their respective Lagrange multipliers  $u_p$  and  $u_q$  such that

## **Stability conditions**

Lagrange multipliers  $u_1 = \frac{1}{4}(2\lambda_1 - \lambda_4), u_2 = \frac{1}{4}(2\lambda_2 - \lambda_4),$  $u_3 = 0, \mu_4 = \frac{1}{4} \left( \kappa - \lambda_4 \right),$  $\mu_5 = \frac{1}{8} \left( -2\lambda_4 + \lambda_5 + \lambda_6 + \sqrt{(\lambda_5 - \lambda_6)^2 + \lambda_7^2} \right),$ where  $\kappa = \frac{1}{2} (\lambda_5 + \lambda_6 - \sqrt{(\lambda_5 - \lambda_6)^2 + \lambda_7^2}).$ 

If  $u_1$  is the smallest value  $\Rightarrow \lambda_1 + \lambda_3 > 0$  necessary If  $u_2$  is the smallest value  $\Rightarrow \lambda_2 + \lambda_3 > 0$ 

If  $u_3 = 0 < u_1, u_2, \mu_4, \mu_5$ , then  $\lambda_4 > -2\lambda_3 - 2\sqrt{(\lambda_1 + \lambda_3)(\lambda_2 + \lambda_3)}$ sufficient If  $\mu_4 < u_1, u_2, u_3, \mu_5,$  then  $\kappa > -2\lambda_3 - 2\langle (\lambda_1 + \lambda_3)(\lambda_2 + \lambda_3) \rangle$ 

- $K_3 = \varphi_1^{\dagger} \varphi_1 \varphi_2^{\dagger} \varphi_2, \ K_2 = 2 \operatorname{Im} \varphi_1^{\dagger} \varphi_2$ General THDM Higgs potential :  $V(\varphi_1,\varphi_2) = V_2 + V_4$  $V_2 = \xi_0 K_0 + \xi_a K_a$ with  $V_4 = \eta_{00} K_0^2 + 2K_0 \eta_a K_a + K_a \eta_{ab} K_b$
- No gauge d.o.f. in this scheme, reduced powers

#### **Orbit Variables**

• Domain $(\mathbf{K} \equiv (K_1 K_2 K_3)^T)$ :  $K_0 = ||\varphi_1||^2 + ||\varphi_2||^2 \ge 0$  $K_0^2 - K^2 = 4 \left( ||\varphi_1||^2 ||\varphi_2||^2 - |\varphi_1^{\dagger} \varphi_2|^2 \right) \ge 0$ • Change of doublet basis by  $U \in U(2)$  $\left(\varphi_1' \; \varphi_2'\right)^T = U \left(\varphi_1 \; \varphi_2\right)^T,$ means for orbit variables  $K'_0 = K_0$ ,  $\mathbf{K}' = R(U)\mathbf{K}, \ R(U) \in SO(3),$  $U^{\dagger}\sigma^{a}U = R_{ab}(U)\sigma^{b}.$ • Minkowski type structure:  $(K_0, \mathbf{K})$  on and inside "forward light cone".

 $(E-u_p)\mathbf{p}=-\boldsymbol{\eta},$  $(E-u_a)\mathbf{q}=-\boldsymbol{\eta},$ 

where

$$|\mathbf{p}| = 1, \quad |\mathbf{q}| = 1 \quad \text{and} \quad u_p \neq u_q$$

is concluded that

 $u_p < u_q \iff J_4(\mathbf{p}) < J_4(\mathbf{q}).$ 

- it makes it easier to find the conditions of the parameters to have a stable scalar potential:
  - computed all the "regular" and "exceptional" Lagrange multipliers,
  - takes, from them, the smallest value, or assuming that each one of them is the lowest value.
  - if the smallest value is a regular solution, the condition  $J_4(\mathbf{p}_i) > 0$  would guarantee the stability of the scalar potential.
  - If the smallest value is an exceptional solution, you must first verify that it gives a valid stationary point. In the case of being satisfied, impose the condition  $J_4(\mathbf{p}_i) > 0$ , which would guarantee the stability of the potential.
- conditions coming from regular solutions are necessary.
- conditions arising from the exceptional solutions may not be necessary, they are sufficient.

#### **Conclusions**

We can see that the application of the result (1) is essential to get a consistent model and be able to derive sufficient conditions to have a stable scalar potential. It allows us to identify either necessary conditions (for regular solutions) or conditions that may not be necessary, coming from exceptional solutions (including 0). Both conditions generate sufficient inequalities that guarantee the stability of a scalar potential. As an example, we can appreciate it, in the expression (152) of Ref. [1], where  $u_2 < u_1, u_3$ , so for stability conditions, only  $u_2$  is considered. In this sense, it may happen that some Lagrange multipliers, although not being the smallest values, must be taken into account for stability conditions. You can appreciate it from Gunion's potential (Eq. (79) of Ref. [1]), since if  $\mu_4$  were not a valid stationary point, we would have had to analyze  $\mu_5$ . In that way, we can reduce the number of sufficient conditions arising from exceptional solutions (including 0) provided that  $J'(k_i) < 0$  (or  $J'(0) \le 0$ ).

#### References

(1)



 $K_0$ 

[1] Maniatis M, von Manteuffel A, Nachtmann O and Nagel F 2006 Eur. Phys. J. C48 805–823 (Preprint hep-ph/0605184) [2] Nagel F 2004 New aspects of gauge-boson couplings and the Higgs sector Ph.D. thesis Heidelberg U. URL http://www.ub.uni-heidelberg.de/archiv/4803